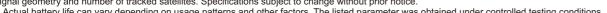
Specifications

| Specifications | | | | | | | | | | |
|-------------------------------|---|-------|---|---|---|---|---|--|---|--|
| GNSS | Signal Tracking(1598) | | | S | Signal Tracking(1698) | | | Signal Tracking(1760) | | |
| Performances | 1598 channels GPS: L1, L1C, L2C, L2P, L5 GLONASS: L1C/A,L1P,L2C/A,L2P,L3 BDS: BDS-2: B11, B21, B31, BDS-3: B11, B31, B1C, B2a, B2b* GALILEO: E1, E5A, E5B, E6C, AltBOC* SBAS(WAAS/MSAS/EGNOS/GAGAN): L1* IRNSS: L5* QZSS: L1, L2C, L5* MSS L-Band: BDS-PPP, Galileo HAS | | | | 1698 channels GPS: L1, L1C, L2C, L2P, L5 GLONASS: G1, G2, G3 BDS: B11, B21, B3L, B1C, B2A, B2B* GALILEO: E1, E5A, E5B, E6C* SBAS(WAAS/MSAS/EGNOS/GAGAN): L1C, L1A* Navic/IRNSS: L5* QZSS: L1, L2C, L5* MSS L-Band: BDS-PPP, GALILEO-HAS | | | 1760 channels GPS: L1C/A, L1C, L2C, L2P, L5 GLONASS: L1C/A, L2C/A, L2P, L3CDMA BDS: B1I, B1C, B2I, B2a, B3 GALILEO: E1, E5A, E5B, E5AltBOC, E6 SBAS: EGNOS, WAAS, GAGAN, MSAS, SDCM(L1,L5) Navic: L5 QZSS: L1C/A, L1C, L2C, L5, L6 MSS L-Band: BDS-PPP, Galileo HAS* | | |
| | Other Features | | | | | | | | | |
| | Time to first fixed: <8s | | | | | | | | | |
| Positioning | Code differential GNSS positioning | | | Static(lo | Static(long observations) | | | atic | | |
| Precision | H: 0.25m+1 ppm RMS V: 0.50m+1 ppm RMS | | | H: 2.5mm+0.1 ppm RMS V: 3mm+0.4 ppm RMS | | | | H: 2.5 mm + 0.5 ppm RMS V: 3.5 mm + 0.5 ppm RMS | | |
| | Rapid static | | | PPK | | | R | RTK(UHF) | | |
| | H: 2.5 mm + 0.5 ppm RMS V: 5 mm + 0.5 ppm RMS | | | H: 3 mm + 1 ppm RMS V: 5 mm + 1 ppm RMS | | | | H: 8 mm + 1 ppm RMS V: 15 mm + 1 ppm RMS | | |
| | RTK(NTRIP) | | | RTK initialization time | | | SE | SBAS positioning | | |
| | H: 8 mm + 0.5 ppm RMS V: 15 mm + 0.5 ppm RMS | | | 2 ~ 8s | | | Typically<5m 3DRMS | | | |
| | BDSPPP | | Galileo HAS | | | | | | | |
| | H:10cm V: 20cm | | | H: 20cm V: 40cm | | | | | | |
| IMU | Update Rate | | Tilt Angle | | Initializati | Initialization Way | | Туре | | |
| | 200Hz | | 0-60° | | Shake or Wa | Shake or Walk | | Calibration Free | | |
| User Interface | Keys T | | Touch So | creen | LED | LED | | WEB UI | | |
| | Power Key | | HD 1.39inches color circle touch screen | | Power Indica | Power Indicator | | Supported | | |
| | Voice Guidence Language | | e Supported | | | | | | | |
| | Supported Chinese, En | | | glish, Korean, Russian, Spanish, Portuguese, Turkish, French, Italian | | | | | | |
| | Operating system Seconda | | ry development | ry development | | | Cloud service | | | |
| | | | | secondary development package and ope on data format and interaction interface de | | | | | werful cloud platform provides online services ent, firmware update, online register, etc. | |
| Hardware | Dimension Weight | | ht | Material | Temperatur | e Humidity | | ty | Waterproof/Dustproof Shock/Vibration | |
| | 155mm(Φ) *98.5mm(H) | 1.2kg | | Magnesium aluminur alloy shell | num Working: -45℃ to +75℃ Storage: -55℃ to +85 ℃ | | 100% Non IP68 standard; -condensing Withstand 2m pole drop onto the cement ground naturally | | Withstand 2m pole drop onto | |
| | Power Supply | | | Battery ¹ | | | | | | |
| | 6-18V DC, overvoltage protection | | | | Built-in 7.4V 10000mAh, PD quick charge protocol; rover data collector internet mode>20h | | | | | |
| | Electronic bubble | | | | Thermome | Thermometer | | | | |
| | Controller software can display electronic bubble leveling status of the carbon pole in real-time | | | e, checking Built-in thermometer sensor monitoring and adjusting the | | | , adopting intelligent temperature control technology, e receiver temperature | | | |
| AR Stakeout Camera | Pixel Visua 2M 75° | | al Angle | Visual Position | Visual Positioning Camera | | Pixel 8M | | | |
| Communication | I/O Ports | | | Radio | | | WIFI | | | |
| | 5-PIN LEMO (external power port + RS232) Type-C(charge+USB+OTG+Ethernet) UHF antenna interface | | | 1W/2W/3W Radio receiver and transmitter Frequenge: 403-473MHz Protocol: Farlink, SOUTH, TrimTalk, Hi-target, HI Radio router, Radio repeater Range: With Farlink protocol, up to 15km | | Hi-target, HUAC | Support AP mode and Client mode | | | |
| | Cellular Network | | | NFC | | | B | ВТ | | |
| | 4G LTE, 3G WCDMA, 2G GPRS, GSM | | | Automatic pair between receiver and controller (controller requires NFC wireless communication module) | | | | Bluetooth 4.0 standard, Bluetooth 2.1+EDR | | |
| Data Storage /Transmission | Storage | | | Data transmission | | Data Fo | Data Formats | | | |
| | 64GB SSD internal storage Automatic cycle storage Support external USB storage The customizable sample interval is up to 50Hz | | | Plug and play mode of USB data transmission Supports FTP/HTTP data download | | Static data format: STH, Rinex2.01, Rinex3.02 and etc. Differential data format: RTCM 2.1, RTCM 2.3, RTCM 3.0, RTCM 3.1, RTCM 3.2 GPS output data format: NMEA 0183, PJK plane coordinate, Binary code Network model support: VRS, FKP, MAC, fully support NTRIP protocol | | | | |
| | | | | | | | | | | |

*Reserve for future upgrade.

Remarks: Measurement accuracy and operation range might vary due to atmospheric conditions, signal multipath, obstructions, observation time, temperature, signal geometry and number of tracked satellites. Specifications subject to change without prior notice.

1. Actual battery life can vary depending on usage patterns and other factors. The listed parameter was obtained under controlled testing conditions.



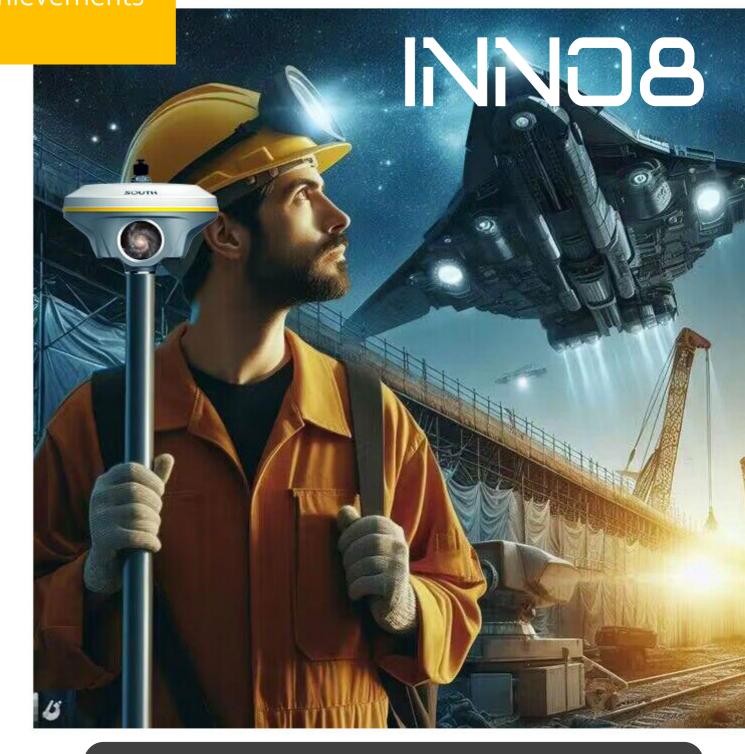


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We Wish You Great Achievements





- ✓ Visual Positioning & Stakeout ✓ 3D Modeling
- ✓ 3 Ways of Processing

- ✓ Up to 1760 channels
- ✓ Farlink 2.0
- ✓ 4th generation IMU

The Unique UAV Photogrammetry Algorithms from SOUTH is Adding 10 Advantages to Traditional GNSS RTK

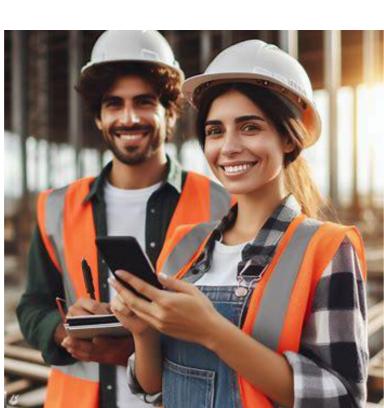


More Points Collected in Less Time, With Less Blind Spots

More Efficient than Traditional RTK

- SOUTH Group has accumulated a decade of experience in the development of UAV photogrammetry solutions. This has led to the creation of a unique and efficient photogrammetry algorithm for INNO8. This allows INNO8 to directly collect both image and coordinate data. Users can capture still photos or shoot videos while walking. With just one group of photos or a video, users can obtain coordinates for all target points within the measurable range, measuring hundreds of points in few minutes.
- Compared to traditional photogrammetry equipment, INNO8's data acquisition speed is faster. After collecting photos or videos, users can perform real-time automatic processing by using data collection App on controller. This allows users to obtain coordinates without the need for PC post-processing software, especially in time-sensitive situations.
- Compared to traditional RTK, INNO8 has a broader working range and fewer blind spots. By photogrammetry function, surveyors can remotely measure points that are without GNSS signal or poor signal quality, from a well-signaled position. Points without satellite signals, such as spaces under rooftops, can now be measured. Previously challenging blind spots or places with severe multipath effects like dense tree areas or construction sites with multiple obstacles, are now easier to measure.







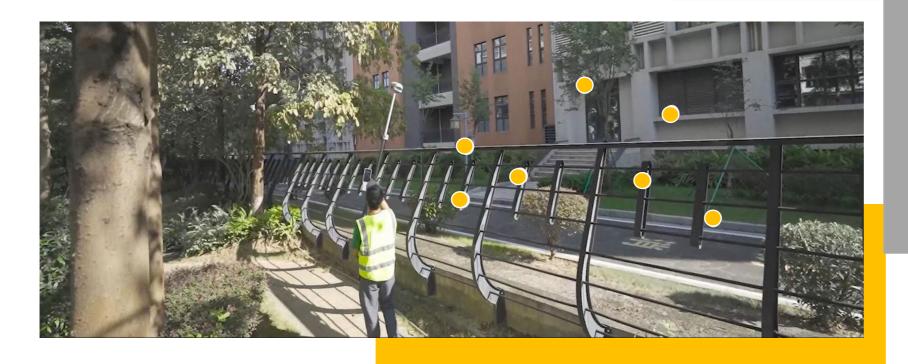
Easy to Learn, Effortless to Use, and Uncomplicated for Re-measurement

More User-friendly than Traditional RTK

- √ When surveyors process photos in the controller App, they simply need to click on the same point in just three photos to calculate the coordinates. This operation is quite easy to learn.
- √ A notable feature of photogrammetry is labor-saving. When using INNO8, surveyors can achieve remote measurements at distances of up to 10 meters or even more (in ideal condition), eliminating the need to physically approach each measurement point. This working method significantly saves the surveyor's physical effort, reducing the labor involved in fieldwork.
- $\sqrt{}$ In cases some data needs to be remeasured, surveyors do not have to return to the field. They can simply click on the saved photos to obtain coordinates, making re-measurement a hassle-free



The Unique UAV Photogrammetry Algorithms from SOUTH is Adding 10 Advantages to Traditional GNSS RTK



Wide Applications, Abundant Output, Satisfying Return in Investment

More Versatile than Traditional RTK

- Utilizing visual positioning, surveyors can work at a rapid pace in the field. Image data can be stored for a long period and reused at any time. These features are particularly suitable for unconventional GNSS measurement tasks such as recording accident scenes and excavation sites for urban public facilities.
- √ When using in conjunction with SOUTH UAV, SGO, or other third-party post-processing software, INNO8 not only outputs coordinates but also various types of data such as images, 3D models, point clouds, and supports multiple coordinate systems. This feature meets your diverse application needs for various types of data and provides a richer output of results.
- Considering the investment perspective, INNO8 stands out as a more cost-effective and versatile option for surveying tasks, compared to other measurement equipment such as laser scanners.



Your Safety, We Care

Safer than Traditional RTK

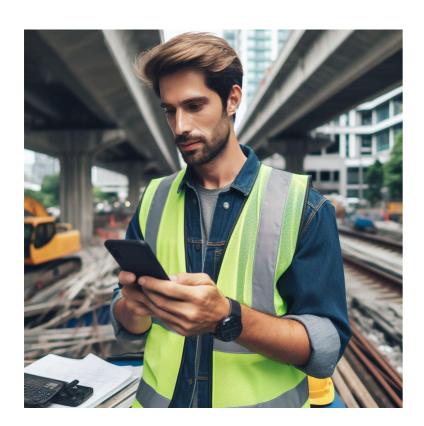
- During measurements along the edges and central areas of busy roads, safety risks are present for surveyors. To minimize these risks, surveyors can utilize INNO8 visual positioning to maintain a safe distance from hazardous locations while completing their work, ensuring maximum safety.
- √ During measurements, the potential hazards of conducting surveys near water bodies, like rivers and lakes, should not be underestimated. Visual positioning aids users in mitigating risks in comparable scenarios, ensuring their safety. Ensuring a secure working approach is not just a personal requirement but also a necessity for the well-being of your family.





Three Types of Image Data Processing Modes

- Carefully Designed for Your Challenging Work Requirements



Cloud Server Online Processing, Balancing Performance and Efficiency

Designed for Urban Surveying

When surveyors have a high-quality internet connection, they can process image data online through the network and cloud servers. INNO8 can obtain coordinate data for image measurements with 2cm accuracy in just a few minutes. This processing mode balances high accuracy and fast processing speed.



Desktop Software Processing, Leave More Time for Fieldwork

Designed for Users with Tight Fieldwork Schedules

Sometimes, surveyors have limited time for fieldwork and need to collect the maximum amount of data in the shortest possible time. In such cases, they can choose not to process data on-site but instead use desktop data post-processing software to process image data after returning to the office.

This working mode offers richer measurement and calculation functionalities, comprehensive data applications, allowing users to focus on data collection outdoors, achieving the highest point acquisition speed, and making the most of their time.



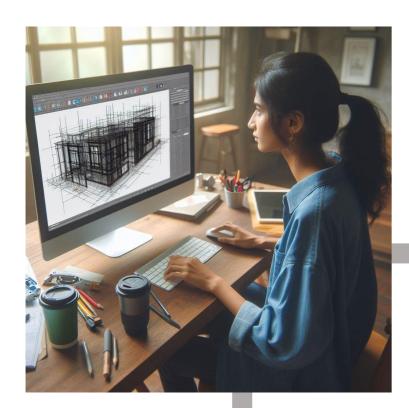


Data Controller Offline Processing, What You See is What You Get

Designed for Field Surveying

When outside the coverage area of internet, surveyors can achieve offline processing of image data through the data controller app. This processing mode boosts the fastest processing speed by saving time of uploading image data, providing 4cm accuracy results within 30 seconds.

3D Modeling—Broadening Your Working Power is Our Duty and Privilege



One-Man 3D Modeling

Eyes on Now, Be Prepared for Future

With INNO8, single-user standalone operation is sufficient to achieve 3D modeling, visually presenting geographic information data such as coordinates, areas, and volumes. Model data can be transformed into different formats and applied with various coordinate parameters based on actual needs, making it adaptable to a wider range of application scenarios.

SOUTHTarget your success

One Data, Multiple Uses

Work in Your Preferred Way

Surveyors can import the data outcomes from INNO8 into SOUTH UAV and other third-party modeling software for 3D modeling.

SGO (PC version) and SurvStar (Android App) will also support 3D modeling function in the future. Users can choose the software that best suits the current scenario and task requirements to achieve the highest work efficiency.





Complement for UAV Survey Data

Ensuring a Smooth Journey for Your Success

SOUTH's 3D modeling technology are fully utilized and transformed in INNO8. The results of image measurements by INNO8, can be seamlessly integrated with data outcomes from DJI and other brand IIAV

UAV surveys often face challenges of data gaps, leading to incomplete model outcomes. In such cases, surveyors can use INNO8 to collect image data on the ground and incorporate it into aerial survey data as a supplement, thereby enhancing the overall model outcome.

AR Stakeout

Stakeout Intuitively with Live-view Video Display

Experience INNO8 AR stakeout by following the real-time, real-scene guidance on the data controller display without continuously watching on the compass or leveling the pole.

In addition to points, INNO8 can handle staking out lines and curves with AR, which broaden its applications and is suitable for more complex work demands. With AR stakeout, you can now achieve quick and precise stakeouts with ease.





Smart LCD Touchscreen

Make Workflow Simpler and Smoother

INNO8 is thoughtfully designed with a user-friendly interface featuring a large touchscreen to:

- √ Quickly touch screen to switch working mode and datalink, without data controller or mobile devices
- $\sqrt{}$ Quickly check system information on receiver screen, no need of other device
- \checkmark Quickly launch PPK measurement program, without handheld controller
- $^{\checkmark}$ Precisely display self-check status on receiver screen, saving time, never miss information



Farlink 2.0

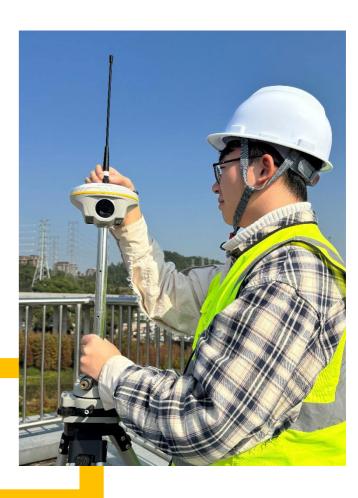
Less Limitation Better Performance

Here comes the Farlink 2.0. After years of hardware and firmware updates, Farlink 2.0 can undertake larger data and provide more stable transmission. Its communication range reach up to 15-20km, being a base can easily cover the working area without moving it frequently.

In addition, Farlink 2.0 can receive data from one specific base. Even though there are several bases transmitting with the same frequency, your rover will receive data from the correct base.

Each radio had extreme temperature-changing testing from $20\,^\circ\!\text{C}$ to $60\,^\circ\!\text{C}$ to protect your device from changing temperature.





The 4th Generation IMU

Almost All-time Usable

In 2023, we introduced two significant updates: Calibrate-free Initialization and Stability Improvement. Moving into 2024, another noteworthy update has been implemented: the IMU sensor now maintains usability when the pole is rotated.

Traditionally, surveyors encountered issues where rotating the pole during changes in travel direction or adjusting receiver attitude would occasionally disable the IMU. The latest update effectively eliminates the loss of Inertial-Measurement-Usable Status in the majority of scenarios, enhancing IMU availability and productivity. During AR stakeout, visual positioning and 3D modeling collection, you can walk with your own pace without worry about losing IMU, making workflow smooth.