



J1 is designed to enhance your performance in the field survey and to provide the most reliable positioning result.

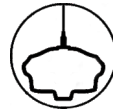
It integrates a 1698 channels world leading GNSS positioning engine, high precision IMU, long range UHF radio and new interact operating system.

More features are to be discovered by you...



J1

Improving Never Stops



More channels and all constellations tracking

With 1698 GNSS channels solution, J1 can support multi-constellation and multi-frequency tracking with the help of high-performance GNSS antenna.

More powerful inbuilt radio

Coupling a high-performance UHF module with Farlink communication technology, which increases signal sensitivity and transmission efficiency, J1 really achieves the goal of a 8~15km ultra-long-distance working range. And the power consumption of this carrying new generation module is 60% lower than additional UHF, making the Base working time is much longer.

Superior Endurance, Up to 25 hours working

J1 uses a built-in 10000mAh ultra-large capacity Li-ion battery, which can last 25 hours of continuous work (Static) benefits from low power consumption circuit design. The Type-C interface is used on J1 that it can support fast charging through a charger with PD protocol, and it can be full charged in 4 hours.

Double data backup

The measured data can be simultaneously stored into both internal memory of receiver and controller, realizing the measured data double backup, which effectively avoid data loss.

Upward and hidden UHF antenna design

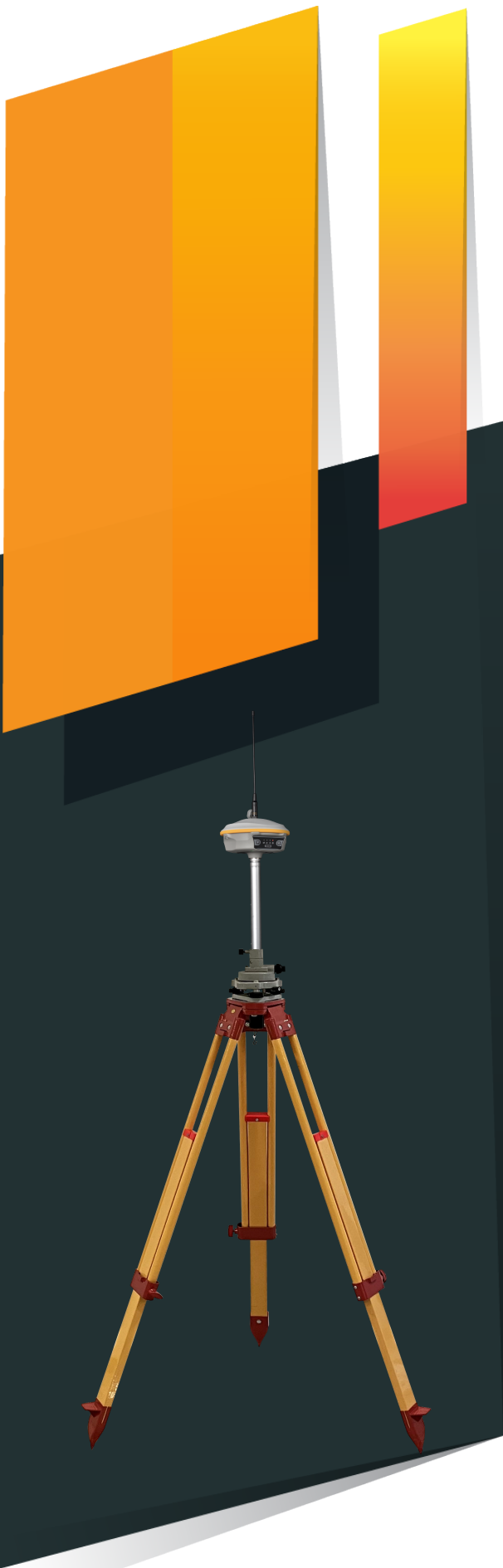
Upward UHF antenna design, achieving all-direction UHF signal receiving and transmitting. And the antenna interface is hidden into top cover that effectively avoid accident breaking, protect from water and dust.

Intelligent base signal locking technology

Using one-to-one signal tracking and locking technology, and the independent frequency under Farlink protocol, the J1 rover can continuously lock and capture the target base station signal to reduce cross-frequency interference even though other base stations are working nearby with the same channel.

Smart system management-ROS

J1 is integrated with the ROS system, which comes with intelligent deployment of multi-mode hardware components, strong computing power and an intelligent scheduling mechanism, and coupling with an ultra-fine memory management mechanism, making the fluency and running speed of the receiver comprehensively improved.



SPECIFICATIONS

GNSS Features

Channels.....	1698
GPS.....	L1C/A, L1C, L2C, L2P, L5
GLONASS.....	G1, G2, G3*(reserved)
BDS.....	B1I, B1C, B2I, B2a, B2b, B3
GALILEO.....	E1, E5A, E5B, E5AltBOC, E6
SBAS.....	EGNOS, WAAS, GAGAN, MSAS, SDCM(L1, L5)
QZSS.....	L1C/A, L1C, L2C, L5, L6
Navic.....	L5*(reserved)
On module L-Band (Reserve)	
Positioning output rate.....	1Hz~20Hz
Initialization time.....	< 10s
Initialization reliability.....	> 99.9%

Positioning Precision*

Real-time kinematic..... Horizontal: 8 mm + 0.5 ppm RMS
(Baseline<40km) Vertical: 15 mm + 1 ppm RMS

GNSS static..... Horizontal: 2.5 mm + 0.5 ppm RMS
Vertical: 5 mm + 0.5 ppm RMS

Standalone..... Horizontal: 1.2m Vertical: 1.9m RMS
DGNSS..... Horizontal: 0.4m Vertical: 0.7m RMS
SBAS positioning..... Horizontal: 0.6m Vertical: 0.8m RMS

Hardware Performance

Dimension.....	165mm(φ) × 108mm(H)
Weight.....	1.35kg (battery included)
Material.....	Magnesium aluminum alloy shell
Operating temperature.....	-45°C ~ +65°C
Storage temperature.....	-45°C ~ +85°C
Humidity.....	100% Non-condensing
Waterproof/Dustproof.....	IP68 standard, protected from long time immersion to depth of 1m IP68 standard, fully protected against blowing dust
Shock/Vibration.....	Withstand 2 meters pole drop onto the cement ground naturally
Power supply.....	9-28V DC, overvoltage protection
Battery.....	Inbuilt 10000mAh rechargeable, unremovable Li-ion battery
Battery life.....	Static: 20~25hrs Base: 10~12hrs Rover: 16~20hrs

Communications

I/O Port.....	5-PIN LEMO external power port + RS232 Type-C interface (charge + OTG + Ethernet) 1 UHF antenna interface 1 PPS output interface SIM card slot (Micro SIM)
Internal UHF.....	5 W receiver and transmitter
Frequency range.....	410 - 470MHz
Communication protocol.....	Farlink, Trimtalk450s, SOUTH, HUACE, Hi-target, Satel
Communication range.....	Typically 8-15km with Farlink protocol
Cellular mobile network.....	4G cellular module standard
Bluetooth.....	Bluetooth 4.2 standard, Bluetooth 2.1 + EDR
NFC Communication.....	Realizing close range (shorter than 10cm) automatic pair between receiver and controller

WIFI

Modem.....	802.11 b/g standard
WIFI hotspot.....	Receiver broadcasts its hotspot form web UI accessing with any mobile terminals

Data Storage/Transmission

Storage.....	16GB SSD internal storage standard, extendable up to 64GB Automatic cycle storage Support external USB storage The customizable sample interval is up to 20Hz
Data transmission.....	Plug and play mode of USB data transmission Supports FTP/HTTP data download
Static data format.....	STH, Rinex2.x, Rinex3.x
Differential data format.....	CMR, RTCM 2.x, RTCM 3.x(MSM included)
Position output data format.....	NMEA0183, PJK plane coordinate, SBF
Network model supports.....	Fully support NTRIP protocol

Sensors

Electronic bubble.....	Controller software can display electronic bubble, checking leveling status of the carbon pole in real-time
Thermometer.....	Built-in thermometer sensor, adopting intelligent temperature control technology, monitoring and adjusting the receiver temperature

User Interaction

Operating system.....	Linux
Buttons.....	Dual-button
Indicators.....	3 LED indicators
Web interaction.....	With the access of the internal web interface management via WiFi or USB connection, users are able to monitor the receiver status and change the configurations freely
Voice guidance.....	It provides status and operation voice guidance,
Secondary development.....	Provides secondary development package, and opens the OpenSIC observation data format and interaction interface definition

**The data comes from the SOUTH GNSS Product Laboratory, and the specific situation is subject to local actual usage.*

